

I. Listing of Claims

1-18 Canceled

19. (Currently Amended) A method for aiding a driver of a vehicle to park the vehicle, the vehicle having a vehicle steering system with a manual steering wheel on which the driver exerts a driver steering torque and a steering torque control module, the method comprising the ~~step of~~ steps of:

applying, by means of the steering torque control module, ~~a steering~~ an additional steering torque superimposed on the driver steering torque; ~~exerted on the steering wheel by the driver~~ and

varying the additional steering torque in negative ~~correlation to~~ causal dependence on the speed at which the manual steering wheel is turned by the driver.

20. (Previously Presented) The method according to claim 19, wherein the additional steering torque applied to the steering wheel generates one or more artificial steering stops.

21. (Previously Presented) The method according to claim 19, wherein the driver is guided by the additional steering torque applied to the steering wheel during steering maneuvers in a parking procedure in a parking maneuver.

22. (Currently Amended) The method according to claim 21, wherein the additional steering torque applied to the steering wheel is limited as a function of a steering work applied by the driver or a quantity depending thereon.

23. (Canceled)

24. (Previously Presented) The method according to claim 19, wherein changes in restore torques of the steering applied as a function of the steering angle are determined and the additional steering torque is applied to the steering wheel, taking into account the changes in the restore torques by which a driver of the vehicle is supported during a parking maneuver.

25. (Previously Presented) The method according to claim 24, wherein the additional steering torque applied to the steering wheel generates two or more additional steering stops, and the driver is guided by the additional steering torque applied to the steering wheel during a steering maneuver in the parking procedure.

26. (Currently Amended) The method according to claim 24, wherein the additional steering torque applied to the steering wheel is adjusted as a function of a steering work applied by the driver or a quantity dependent thereon.

27. (Canceled).

28. (Previously Presented) The method according to claim 19, further comprising a longitudinal dynamics control module for controlling a speed of the vehicle in maneuvering into a parking space by automatic braking intervention measures as a

function of a position of an accelerator pedal of the motor vehicle.

29. (Previously Presented) The method according to claim 28, wherein when parking in a parking space, the speed of the vehicle is controlled by additional intervention into an engine torque of a drive engine of the vehicle as a function of the position of the brake pedal.

30. (Previously Presented) The method according to claim 28, wherein when maneuvering into a parking space, the speed of the vehicle is controlled by additional intervention into the engine torque of the drive engine of the vehicle and by automatic gear-shifting of the vehicle transmission as a function of the position of the brake pedal.

31. (Previously Presented) The method according to claim 28, wherein when an end of the parking space is detected, the vehicle is automatically braked on reaching the end or shortly before reaching the end of the parking space.

32. (Canceled)

33. (Canceled)

34. (Canceled)

35. (Canceled)